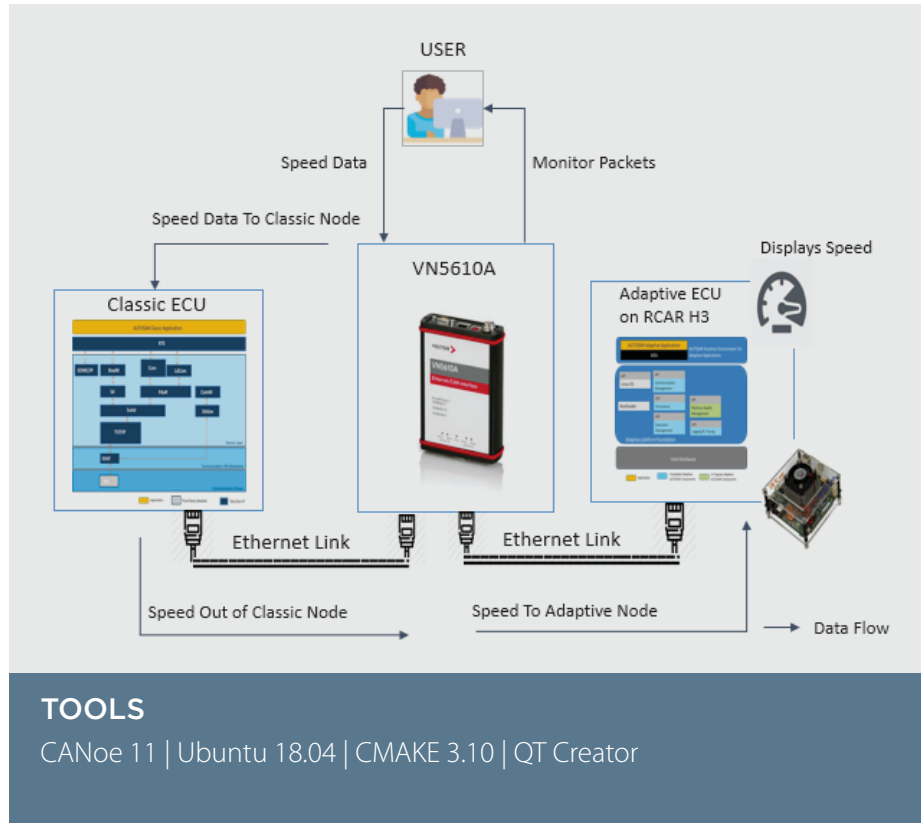


OVERVIEW

A demo application that showcases service oriented communication between AUTOSAR Adaptive node running on R-CAR platform and AUTOSAR Classic node running on Linux.

SCOPE

- The Classic node provides a service which when subscribed, sends speed information via an event. The Adaptive node subscribes to this service and displays the speed using a speed gauge
- Functional Clusters used: Communication management, execution management, logging and tracing, persistency
- Configure: Applications, service interfaces, and machine using the configuration tool
- Generate the manifest files, proxy and skeleton and integrate/ build using CMake



TOOLS

CANoe 11 | Ubuntu 18.04 | CMAKE 3.10 | QT Creator